M415D

Stepper Motor Driver Specification

Overview

The M415D is a new generation microstep stepper motor driver which applies original imported chips. Due to the adoption of the advanced bipolar constant-current chopper driver technology, it shows stable operation, provides excellent high torque. Moreover, it significantly reduces the noises and vibration of the operating motor. The M415D has the feature of low-noise, low-vibration and low-heating. The M415D is DC18-40V power supply. It applies to 2-phase hybrid stepper motor under 1.5A current, such as 57,42series stepper motor. The M415D has several kinds of microsteps. The maximum step number is 12800 steps/rev (microstep is 1/64). The peak operating current ranges from 0.21A to 1.5A., and the output current has 7 stalls. The M415D has automatic semi-flow, motor misconnected protection functions and so on.

Applications

It can be applied in a variety of small scale automation equipment and instruments, such as labeling machine, cutting machine, packing machine, drawing machine, engraving machine, CNC machine and so on. It always performs well when it is used in equipment which requires for low-vibration, low-noise, high-precision and high-velocity.

Current selection

Peak	SW1	SW2	SW3
0.21A	off	on	on
0.42A	on	off	on
0.63A	off	off	on
0.84A	off	on	off
1.05A	off	on	on
1.26A	on	off	off
1.50A	off	off	off

Microstep selection

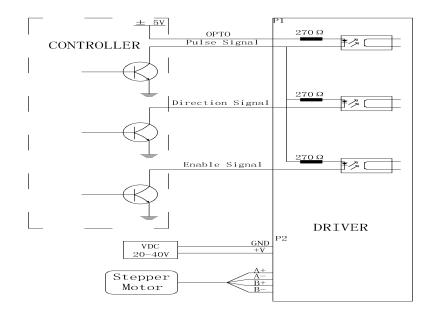
Pulse/Rev	SW4	SW5	SW6
200	on	on	on
400	off	on	on
800	on	off	on
1600	off	off	on
3200	on	on	off
6400	off	on	off
12800	on	off	off

Driver functions descriptions

Driver function	Operating instructions		
Output	Users can set the driver output current by SW1-SW3 three switches.		
current	The setting of the specific output current, please refer to the		
setting	instructions of the driver panel figure.		
Microstep setting	Users can set the driver Microstep by the SW4-SW6 three switches. The setting of the specific Microstep subdivision, please refer to the instructions of the driver panel figure.		
Signal interfaces	PUL is the setting pulse input; DIR is the stepper motor direction input; OPTO is the power supply for signal port + 5V; ENA is the motor free input.		
Motor interfaces	A+ and A- are connected to a phase winding of motor; B+ and B- are connected to another phase winding of motor. If you need to backward, one of the phase windings can be reversed.		
Power interfaces	It uses DC power supply. Recommended operating voltage is 18VDC-40VDC, and power consumption should be greater than 100W.		
Installation instructions	Driver dimensions: $86 \times 55 \times 20$ mm, please refer to dimensions diagram. Please leave 10CM space for heat dissipation. During installation, it should be close to the metal cabinet for heat dissipation.		

Signal interface details:

The internal interface circuits of the driver are isolated by the opt coupler signals, R in the figure is an external current limiting resistor. The connection is differential. And it has a good anti-jamming performance.



Control signal and external interface:

Signal amplitudes	External current	
	limiting resistor R	
5V	Without R	
12V	680 Ω	
24V	1.8ΚΩ	

Outline and installation size (unit: mm)

